

## AM CAR RADIO RECEIVER CIRCUIT

The TEA5550 is an a.m. radio circuit, primarily intended for use in car radios.

The IC can reduce the costs in a car radio due to the following features:

- minimum periphery
- no extra r.f.-prestage is necessary
- ceramic i.f. filter is used
- simple on/off switching method allows inexpensive band switching in a.m./f.m. radios

The TEA5550 incorporates the following functions:

- a double balanced mixer with large signal handling range and common mode rejection properties
- a 'one-pin' oscillator, permitting the use of variable capacitance diode tuning
- an i.f. amplifier, designed for ceramic filters
- an a.m. envelope detector
- a.g.c. stages
- a voltage stabilizer, for supplying the internal circuit current and an external current up to 20 mA
- a simple d.c. switch for a.m./f.m. radios

purple binder, tab 2

### QUICK REFERENCE DATA

Supply voltage range; unstabilized (pin 8)	$V_p$	typ.	10,2 to 18 V
Supply voltage; stabilized (pin 9) *	$V_{stab}$	typ.	8,2 V
Ambient temperature	$T_{amb}$	typ.	25 °C
Supply voltage (pin 8)	$V_p$	typ.	14,4 V
R.F. condition: $f_i = 1$ MHz; $m = 0,3$ ; $f_m = 1$ kHz			
R.F. input voltage (pin 1)			
$V_o = 30$ mV	$V_i$	typ.	4 $\mu$ V
S/N = 26 dB	$V_i$	typ.	16 $\mu$ V
S/N = 46 dB	$V_i$	typ.	160 $\mu$ V
A.F. output voltage (pin 10)			
$V_i = 10$ mV	$V_o$	typ.	180 mV
Total harmonic distortion over most of the a.g.c. range; $m = 0,8$	THD	typ.	1,2 %
R.F. signal handling			
THD = 10%; $m = 0,8$	$V_i$	typ.	400 mV
A.G.C. range; change of r.f. input voltage for 10 dB change of a.f. output voltage (reference $V_{i1} = 200$ mV)	$V_{i1}/V_{i2}$	typ.	86 dB

\* Pins 8 and 9 have to be short-circuited.

### PACKAGE OUTLINE

16-lead DIL; plastic (SOT-38).



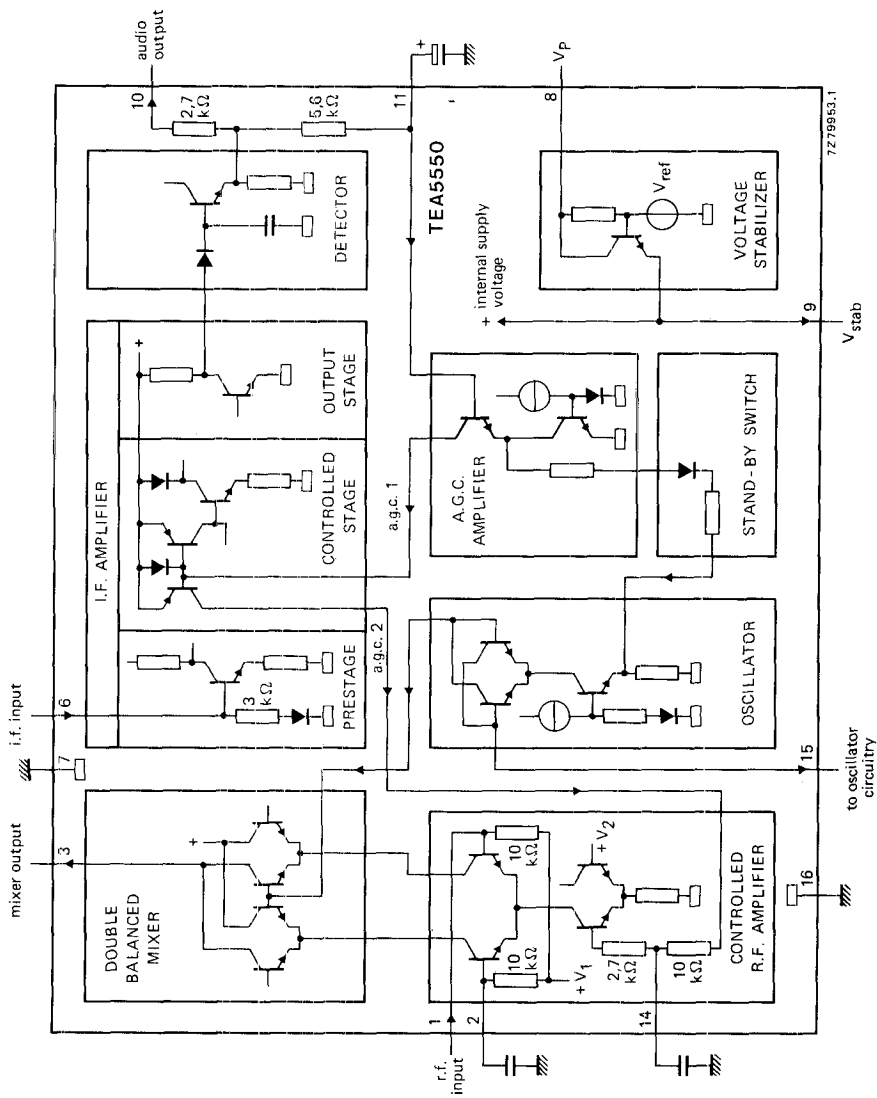


Fig. 1 Block diagram.



## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Supply voltages			
pin 8	$V_P = V_{8-16}$	max.	24 V
pin 3	$V_{3-16}$	max.	24 V
Non-repetitive peak output current (pin 9)	$I_{9SM}$	max.	100 mA
Total power dissipation	$P_{tot}$	max.	1100 mW
Storage temperature	$T_{stg}$		-65 to +150 °C
Operating ambient temperature	$T_{amb}$		-30 to +85 °C

## Note

Pins 4, 5, 12 and 13 are not allowed to be connected.

D.C. CHARACTERISTICS at  $V_i = 0$  $V_P = 14,4$  V;  $T_{amb} = 25$  °C; measured in Fig. 2

Supply voltage range (unstabilized)*	$V_P$		10,2 to 18 V
Voltage at pin 9; $-I_g = 0$	$V_{9-16} = V_{stab}$	typ.	8,5 V 7,5 to 9 V
Change in stabilization voltage (pin 9)			
at $-I_g = 0$ to 20 mA	$\Delta V_{9-16} = \Delta V_{stab}$	typ.	50 mV
at $V_P = 10,2$ to 14,4 V	$\Delta V_{9-16} = \Delta V_{stab}$	typ.	300 mV
Voltage at pin 10	$V_{10-16}$	typ.	1,1 V
Voltage at pins 1 and 2	$V_{1-16} = V_{2-16}$	typ.	5,0 V
Voltage at pin 15	$V_{15-16}$	typ.	$V_{stab}$
Total supply current; $-I_g = 0$	$I_{tot}$	typ.	20 mA
Current drain			
pin 3	$I_3$	typ.	1 mA
pin 15	$I_{15}$	typ.	0,2 mA
Current supplied from pin 9	$-I_g$	<	20 mA
Power consumption; $-I_g = 0$	$P$	typ.	300 mW

DEVELOPMENT SAMPLE DATA

\* A stabilized supply voltage of 7,5 to 9 V can also be applied at pin 9 (pin 8 short-circuited to pin 9).



## A.C. CHARACTERISTICS

$V_P = 14,4 \text{ V}$ ;  $T_{\text{amb}} = 25 \text{ }^\circ\text{C}$ ; r.f. condition:  $f_i = 1 \text{ MHz}$ ,  $m = 0,3$ ,  $f_m = 1 \text{ kHz}$ ; transfer impedance of the i.f. filter  $Z_{\text{tr}} = v_6/i_3 = 850 \Omega$  (loaded with  $3 \text{ k}\Omega$ ); measured in Fig. 2; unless otherwise specified

R.F. input voltage; $V_O = 30 \text{ mV}$	$V_i$		1,5 to 6,5 $\mu\text{V}$
R.F. sensitivity at $R_S = 25 \Omega$ for:			
$S + N/N = 6 \text{ dB}$	$V_i$	typ.	1,3 $\mu\text{V}$
$S + N/N = 20 \text{ dB}$	$V_i$	typ.	8 $\mu\text{V}$
$S + N/N = 26 \text{ dB}$	$V_i$	}	typ. 16 $\mu\text{V}$
$S + N/N = 46 \text{ dB}$	$V_i$		<
$S + N/N = 50 \text{ dB}$	$V_i$	typ.	160 $\mu\text{V}$
	$V_i$	typ.	350 $\mu\text{V}$
Input conductance at pin 1			
$V_i = 0,1 \text{ mV}$	$g_{ie}$	typ.	0,2 $\text{mS}$
$V_i = 100 \text{ mV}$	$g_{ie}$	typ.	0,1 $\text{mS}$
Input conductance at pin 6	$g_{ie}$	typ.	0,3 $\text{mS}$
Output capacitance at pin 15	$C_{oe}$	typ.	20 $\text{pF}$
A.G.C. range; change of r.f. input voltage for 10 dB change of a.f. output voltage (reference $V_{i1} = 200 \text{ mV}$ )	$V_{i1}/V_{i2}$	typ.	86 $\text{dB}$
A.F. output voltage			
$V_i = 10 \text{ mV}$	$V_O$	>	140 $\text{mV}$
		typ.	180 $\text{mV}$
Spread of a.f. output voltage	$\Delta V_O$	typ.	$\pm 2 \text{ dB}$
A.F. output impedance (pin 10)	$ Z_O $	typ.	2,7 $\text{k}\Omega$
Total harmonic distortion at $m = 0,8$			
$V_i = 16 \mu\text{V}$	THD	<	2,5 %
over most of the a.g.c. range (see also Figs 3 and 10)	THD	typ.	1,2 %
$V_i = 25 \text{ mV}$	THD	typ.	3,5 %
R.F. signal handling capability			
THD = 10%; $m = 0,8$	$V_i$	>	350 $\text{mV}$
		typ.	400 $\text{mV}$
I.F. suppression at $V_O = 30 \text{ mV}$	$\alpha$	>	20 $\text{dB}^*$
		typ.	35 $\text{dB}^*$
Oscillator voltage			
$V_{9-16} = 8 \text{ V}$ ; $f_{\text{osc}} = 1468 \text{ kHz}$	$V_{15-8}$	typ.	250 $\text{mV}$
		<	300 $\text{mV}$

\*  $\alpha = 20 \log \frac{V_{ia}}{V_{ib}}$ , where:  $V_{ia}$  is input voltage at  $f = 468 \text{ kHz}$  and  $V_{ib}$  is input voltage at  $f = 1 \text{ MHz}$ .



DEVELOPMENT SAMPLE DATA

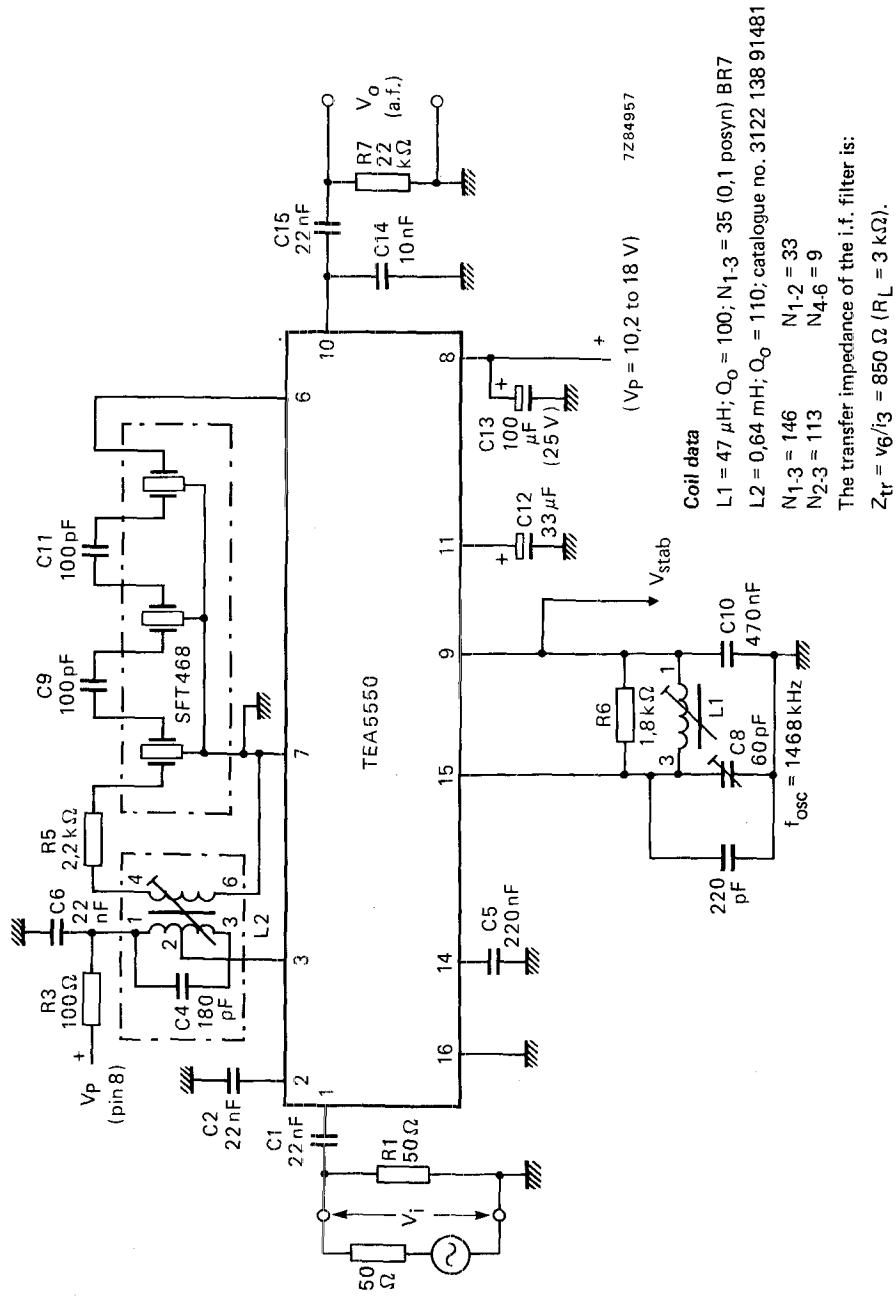


Fig. 2 AM test circuit.



## APPLICATION INFORMATION

Figures 4 and 7 show the circuit diagrams of single-tuned and double-tuned AM channels respectively, using the TEA5550 and an r.f.-tuning unit (type ALPS). The i.f. filter consists of a single-tuned coil in combination with a ceramic filter (type SFT468).

## Typical performance (measured in Figs 4 and 7)

$V_p = 14,4 \text{ V}$ ;  $T_{amb} = 25 \text{ }^\circ\text{C}$ ; aerial signal conditions:  $f_o = 1 \text{ MHz}$ ;  $m = 0,3$ ;  $f_m = 1 \text{ kHz}$  (dummy aerial as shown in Figs 4 and 7)

		Fig. 4 single-tuning	Fig. 6 double-tuning	
R.F. input voltage for:				
S + N/N = 6 dB	$V_i$	4	4	$\mu\text{V}$
S + N/N = 26 dB	$V_i$	47	49	$\mu\text{V}$
A.F. output voltage ( $R_L = R_6 = 22 \text{ k}\Omega$ )				
$V_i = 1 \text{ mV}$	$V_o$	160	160	mV
Signal-to-noise ratio				
$V_i = 1 \text{ mV}$	S/N	> 50	> 50	dB
A.G.C. range; change of r.f. input voltage for 10 dB change of a.f. output voltage (reference $V_{i1} = 200 \text{ mV}$ ); see Figs 3 and 10	$V_{i1}/V_{i2}$	88	88	dB
R.F. signal handling capability THD < 10%; $m = 0,8$ ; see Figs 3 and 10	$V_i$	1,5	1,5	V
Total harmonic distortion (over most of the a.g.c. range); $m = 0,8$ ; see Figs 3 and 10	THD	1,2	1,2	%
Oscillator voltage measured across the tank circuit	$V_{osc}$	250	250	mV
Total selectivity (r.f. and i.f.)	$S_g$	44	46	dB
Total bandwidth (r.f. and i.f.)	$B_{3dB}$	4,1	4,4	kHz
I.F. suppression at $V_i = 20 \mu\text{V}$ tuned frequency = 600 kHz	$\alpha$	55	75	dB
= 1600 kHz	$\alpha$	58	85	dB
Image rejection at $V_i = 20 \mu\text{V}$ tuned frequency = 600 kHz		50	72	dB
= 1000 kHz		46	68	dB
= 1400 kHz		42	64	dB
Whistle at $V_i = 5 \text{ mV}$				
2 x i.f.-tweet		-40	-40	dB
3 x i.f.-tweet		-48	-48	dB



DEVELOPMENT SAMPLE DATA

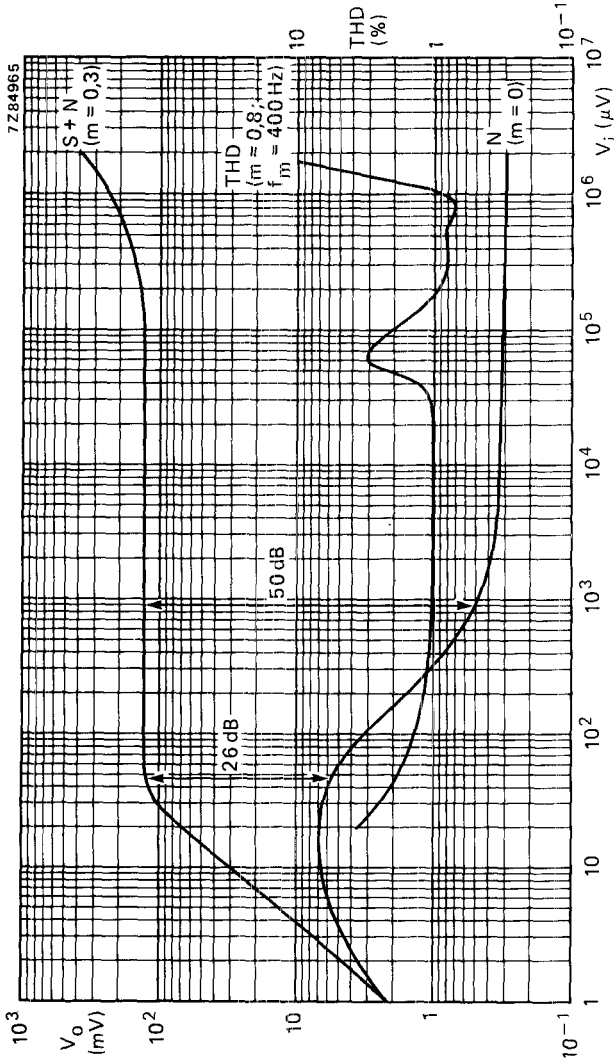


Fig. 3 Typical signal and noise output voltages ( $V_o$  is a.f. output voltage) as a function of the input voltage  $V_i$ . Also shown is the total harmonic distortion (THD). These curves are for a single-tuned AM channel; the dummy aerial is as shown in Fig. 4;  $f_o = 1$  MHz;  $f_m = 1$  kHz;  $m = 0.3$  (unless otherwise specified).



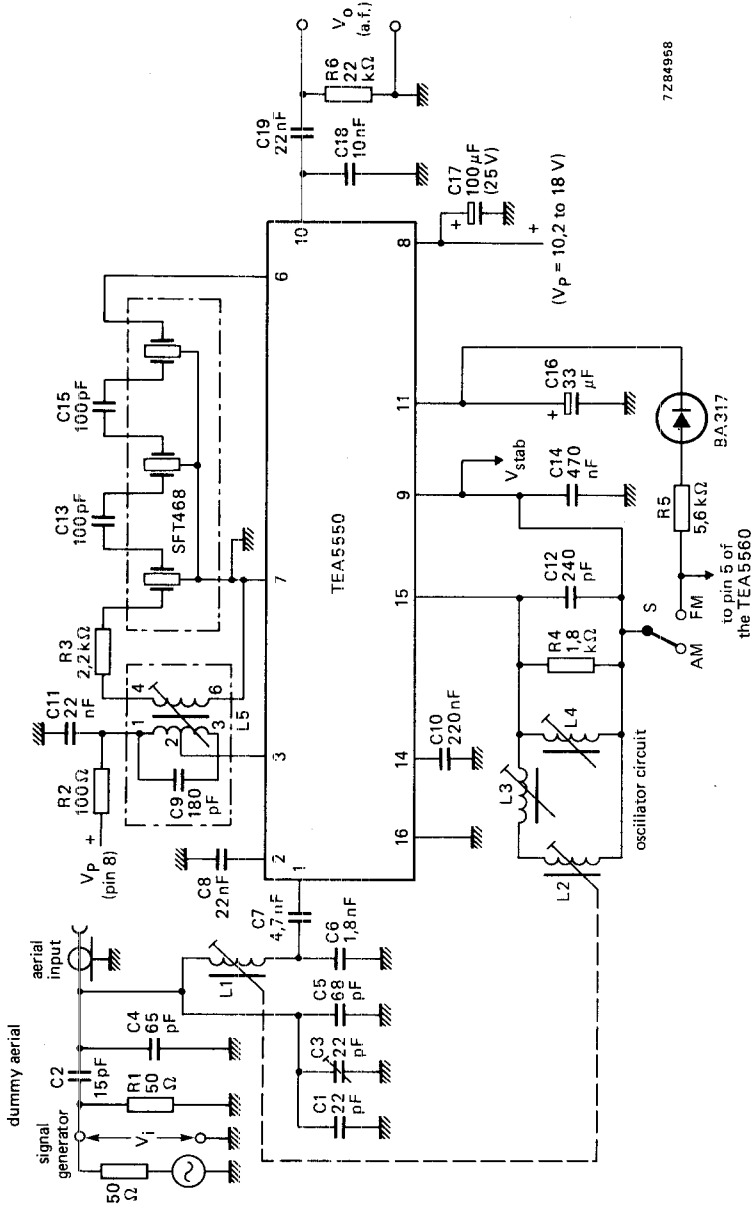


Fig. 4 Typical application circuit diagram for a single-tuned AM channel in car radio receivers using the TEA5550; S is AM/FM switch; for printed-circuit board see Figs 5 and 6.

Coil data: L1, L2 = tuning coils, ALPS unit MMK 11E11 (for coil connections see Fig. 5)

L3 = trimming coil (4.7 μH); catalogue number 3122 138 27460

L4 = padding coil (200 μH); catalogue number 3111 118 23510

L5 = i.f. coil; catalogue number 3122 138 91481





DEVELOPMENT SAMPLE DATA

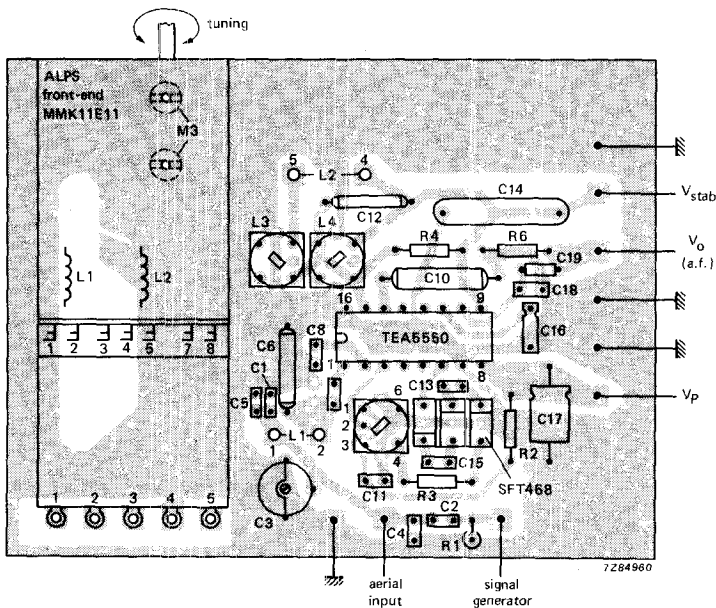


Fig. 5 Printed-circuit board component side, showing component layout. For circuit diagram see Fig. 4.

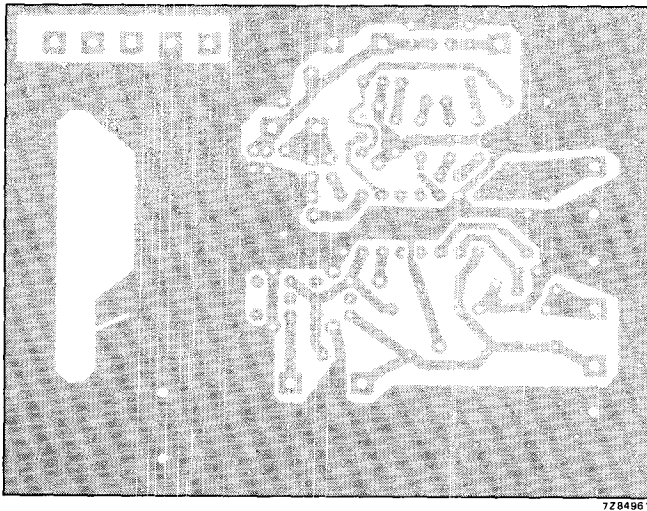
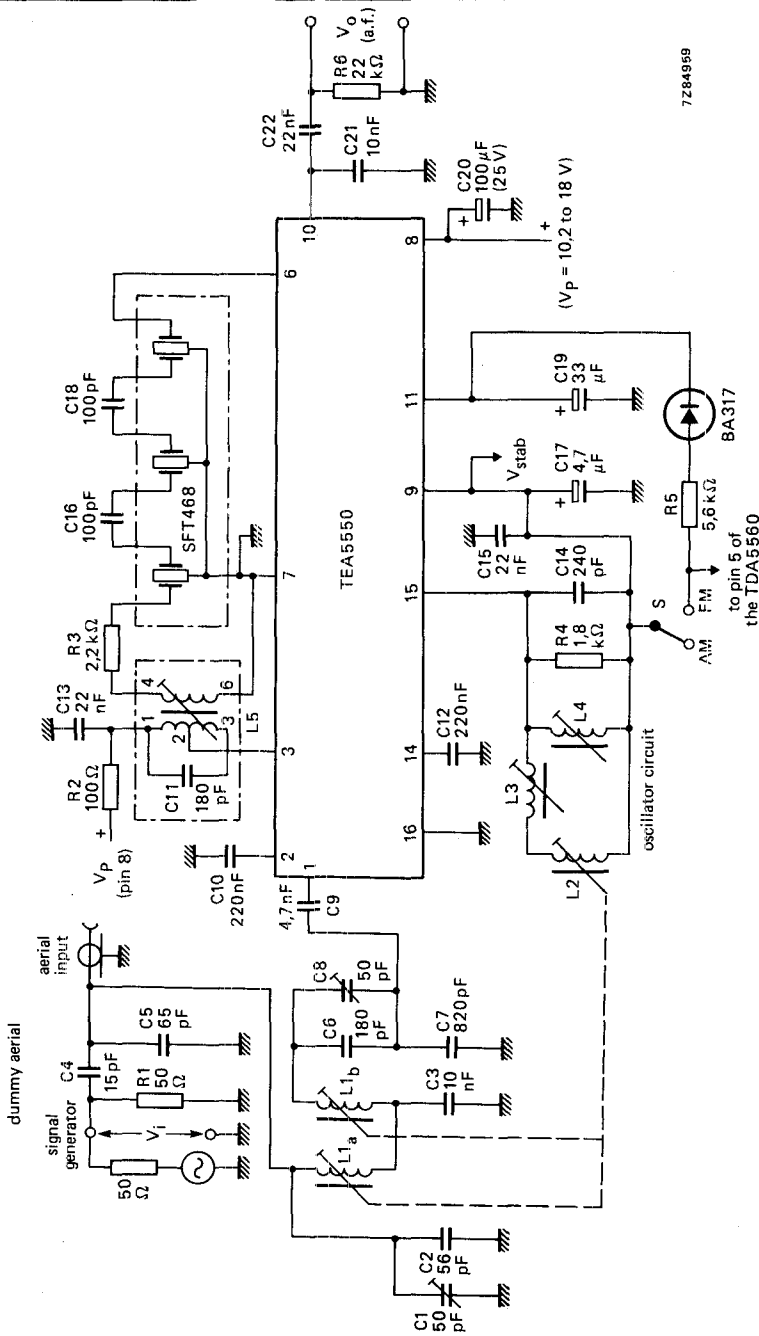


Fig. 6 Printed-circuit board showing track side.





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Fig. 7 Typical application circuit diagram for a double-tuned AM channel in car radio receivers using the TEA5550; S is AM/FM switch, for printed-circuit board see Figs 8 and 9.

- Coil data: L1a, L1b, L2 = tuning coils, ALPS unit MMK IIE II (for coil connections see Fig. 8)  
 L3 = trimming coil (4.7 μH); catalogue number 3122 138 27460  
 L4 = padding coil (200 μH); catalogue number 3111 118 23510  
 L5 = i.f. coil; catalogue number 3122 138 91481



DEVELOPMENT SAMPLE DATA

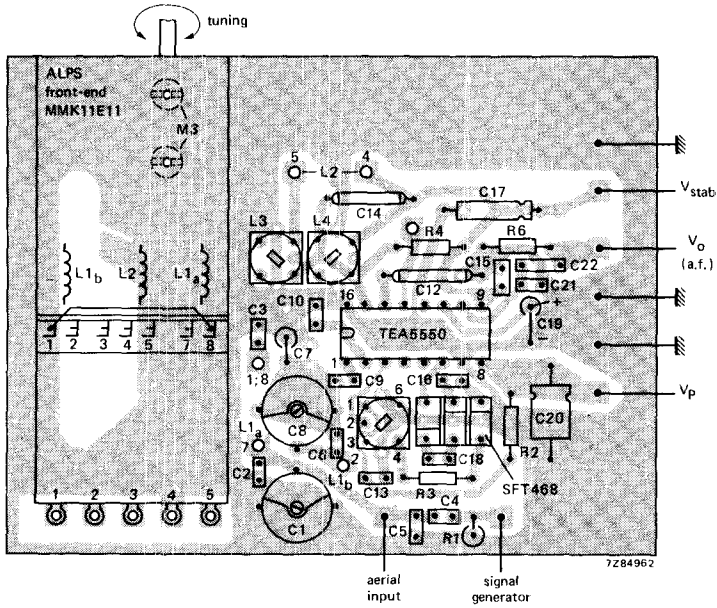


Fig. 8 Printed-circuit board component side, showing component layout. For circuit diagram see Fig. 7.

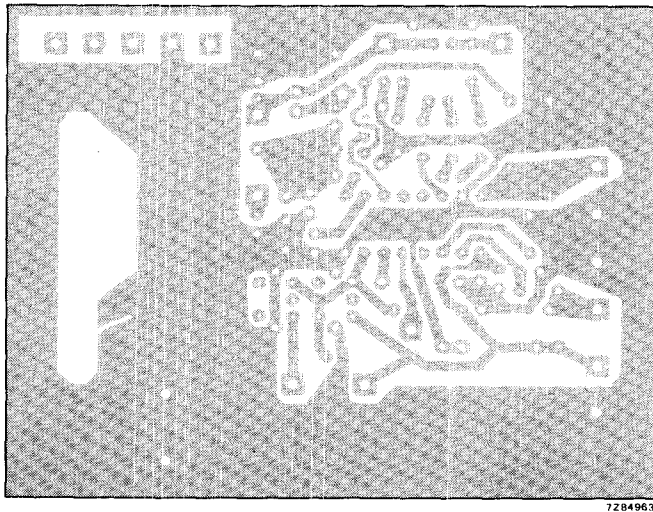


Fig. 9 Printed-circuit board showing track side.



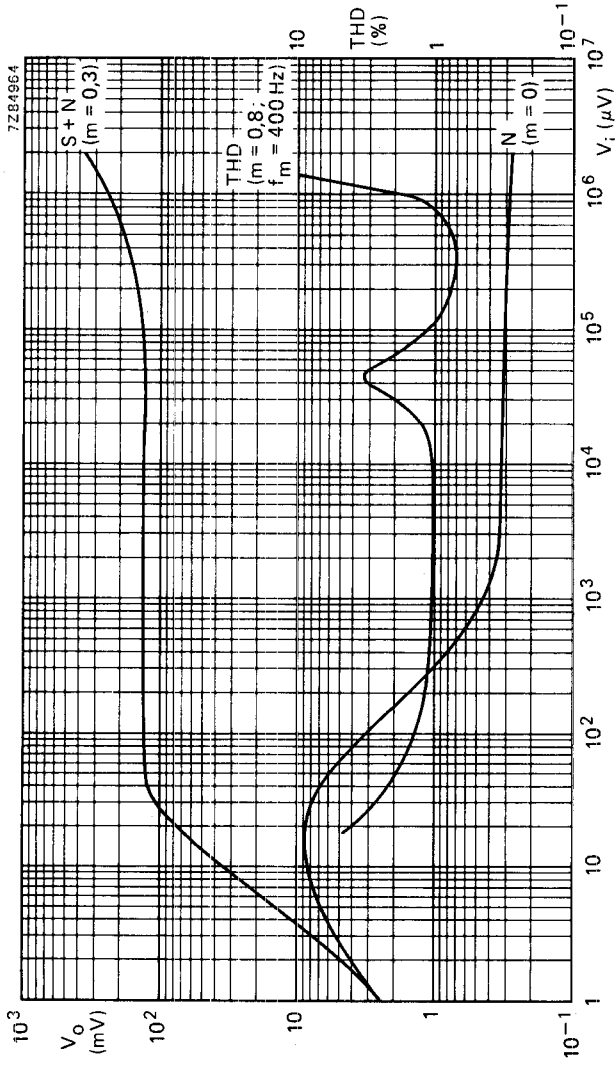
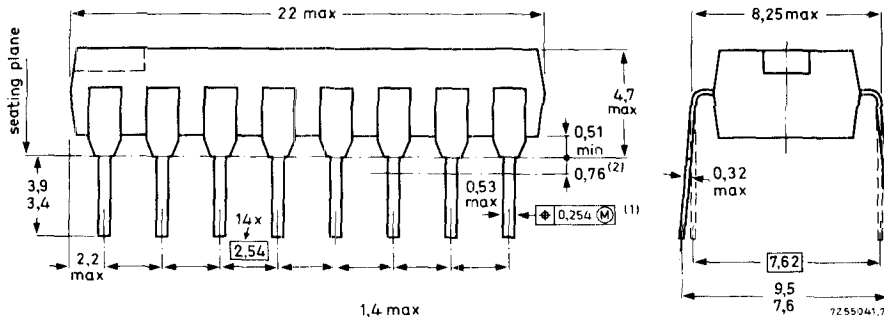


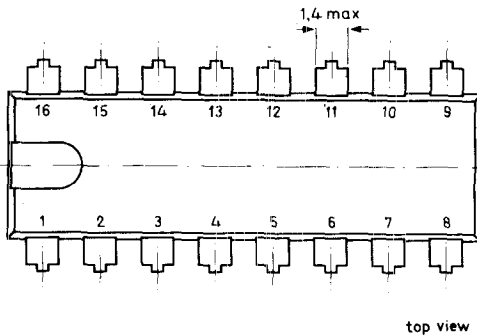
Fig. 10 Typical signal and noise output voltages ( $V_o$  is a.f. output voltage) as a function of the input voltage  $V_i$ . Also shown is the total harmonic distortion (THD). These curves are for a double-tuned AM channel; the dummy aerial is shown in Fig. 7;  $f_o = 1$  MHz;  $f_m = 1$  kHz;  $m = 0,3$  (unless otherwise specified).



16-LEAD DUAL IN-LINE; PLASTIC (SOT-38)



DEVELOPMENT SAMPLE DATA



top view

Dimensions in mm

- ⊕ Positional accuracy.
- Ⓜ Maximum Material Condition.
- (1) Centre-lines of all leads are within  $\pm 0,127$  mm of the nominal position shown; in the worst case, the spacing between any two leads may deviate from nominal by  $\pm 0,254$  mm.
- (2) Lead spacing tolerances apply from seating plane to the line indicated.

**SOLDERING**

**1. By hand**

Apply the soldering iron below the seating plane (or not more than 2 mm above it). If its temperature is below 300 °C it must not be in contact for more than 10 seconds; if between 300 °C and 400 °C, for not more than 5 seconds.

**2. By dip or wave**

The maximum permissible temperature of the solder is 260 °C; this temperature must not be in contact with the joint for more than 5 seconds. The total contact time of successive solder waves must not exceed 5 seconds.  
The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified storage maximum. If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

**3. Repairing soldered joints**

The same precautions and limits apply as in (1) above.

